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1 **Variable rate dosing in precision viticulture: use of electronic**
2 **devices to improve application efficiency**

3 **J. Llorens¹, E. Gil^{1*}, J. Llop¹, A. Escolà²**

4 ¹Dept. Agri Food Engineering and Biotechnology - Universitat Politècnica de Catalunya

5 ²Dept. Agro Forestry Engineering– Universitat de Lleida

6

7 *Abstract*

8 Two different spray application methods were compared in three vine varieties at
9 different crop stages. A conventional spray application with a constant volume rate per
10 unit ground area ($1\cdot\text{ha}^{-1}$) was compared with a variable rate application method designed
11 to compensate electronically for measured variations in canopy dimensions. An air-blast
12 sprayer with individual multi-nozzle spouts was fitted with three ultrasonic sensors and
13 three electro-valves on one side, in order to modify the emitted flow rate of the nozzles
14 according to the variability of canopy dimensions in real time. The purpose of this
15 prototype was to precisely apply the required amount of spray liquid and avoid over
16 dosing. On average, a 58% saving in application volume was achieved with the variable
17 rate method, obtaining similar or even better leaf deposits.

18

19 Key words: Ultrasonic sensor; Vineyard; Canopy volume; Variable rate application;
20 Precision Viticulture; Crop adapted spraying; Vine row volume (VRV).

21

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* Corresponding author: Tel: +34 935 521 099; Fax.: +34 935 521 121
e-mail: Emilio.Gil@upc.edu
Parc Mediterrani de la Tecnologia
Campus del Baix Llobregat UPC
Edifici ESAB – Avda. Canal Olímpic, 15
08860 – Castelldefels (Barcelona) - SPAIN

23 **1. Introduction**

24 The efficiency of plant protection products (PPP) depends on many interacting
25 factors. Crop characteristics (canopy structure, vegetative stage, variety, etc.),
26 application technique, weather conditions, applied dose rate and others are
27 interdependent factors that allow, in an adequate combination, to achieve high efficacy
28 and efficiency values.

29 Crop-adapted dosing of agrochemicals has been widely discussed in many
30 publications (Furness, 2003; Walklate et al., 2003; Gil et al., 2005; Godyn et al., 2005;
31 Viret et al., 2005; Pergher and Petris, 2008). In all cases the main goal has been to adapt
32 the total amount of PPP to crop characteristics but difficulties were encountered in the
33 selection of the most suitable crop parameters. The high degree of variability in crop
34 characteristics has increased the difficulty in obtaining general solutions well adapted to
35 all crops and situations.

36 The use of orchard canopy volume as a basis for chemical application rate
37 calculation and system design was discussed and tested by Sutton and Unrath (1984,
38 1988). The tree row volume concept maintains that chemical rate recommendation and
39 application should be based upon crop canopy volume rather than on land area.
40 Following this methodology other trials have been conducted in order to adapt the spray
41 volume to crop dimensions in vineyards (Siegfried et al., 2007; Pergher and Petris,
42 2008). In all cases, accurate measurements of crop dimensions are a key factor for final
43 success. The use of electronic devices to measure crop dimensions is not a new idea.
44 McConnell et al. (1983) proposed the use of a system with a vertical mast with range
45 transducers to measure tree extension, from the trunk outward and towards the row
46 middle. More recently, Giles et al. (1989), using a modified orchard air-blast sprayer
47 equipped with three ultrasonic transducers, concluded that savings in pesticide

48 application when using the electronic control system was strongly related to target crop
49 architecture. The same authors concluded that sprayer control based upon target
50 measurement, rather than simple target detection resulted in substantial increases in
51 savings of applied spray liquid.

52 To solve the difficulties encountered in crop characterization and to accomplish
53 the recent EU aim to reduce the total amount of PPP (COM, 2006), environmentally-
54 safe spraying techniques have been developed to spray only when and where needed
55 with reduced losses to the environment ((Doruchowski and Holownicki, 2000). Recent
56 advances in computer hardware and software, global navigation satellite systems
57 (GNSS), canopy sensors and remote sensing offer opportunities for fast and inexpensive
58 measurements of tree canopy characteristics for variable rate technologies (VRT)
59 (Zaman and Salyani, 2004). Walklate et al. (2006) using a LIDAR (LIght Detection and
60 Ranging) concluded that area-density and height adjustments were the best crop
61 structure parameters on which a simplified scheme for pome fruit spraying could be
62 based on. Rosell et al. (2009) developed a LIDAR-based measurement system for the
63 estimation of physical and structural characteristics of plants (plant volume, leaf area
64 density and leaf area index). The different shapes, sizes and foliar densities found in tree
65 crops during the same growing season, require a continuous adjustment of the applied
66 dose rate to optimize the spray application efficiency and to reduce environmental
67 contamination (Solanelles et al., 2002). Crop characteristics are directly related to the
68 total amounts of deposit on leaves and values of leaf area and canopy dimensions
69 (mainly height and width) can widely affect the efficiency values, as a relationship
70 between the expected deposit and the actual one (Gil et al., 2005).

71 Target detection has been developed either by using advanced techniques, such
72 as vision systems and laser scanning, or by ultrasonic and spectral systems. Gil et al.

73 (2007) obtained a significant reduction in the total amount of applied volume (57%)
74 using a sprayer prototype with ultrasonic sensors able to measure the crop width
75 variations and to apply a variable dose rate according to the instantaneous measured
76 vine row volume (VRV), in comparison with a conventional and constant application
77 volume rate. However, this reduction did not affect the results in terms of deposit, leaf
78 coverage and penetration where similar normalized values were achieved.

79 Whitney et al. (2002) investigated the ultrasonic transducer's response to
80 different parts of a citrus canopy and also examined the effect of the sampling frequency
81 and the transducer spacing on canopy volume determination. More recently Balsari et
82 al. (2008) using a crop identification system based on ultrasonic sensors, confirmed its
83 suitability for detecting canopy characteristics in real time, independently of the forward
84 speed, as previous studies already indicated (Zaman and Salyani, 2004).

85 It seems that any approach to adapt the spraying volume rate to crop
86 characteristics will lead with a general principle that foliar application must result in
87 similar deposits ($\mu\text{g}\cdot\text{cm}^{-2}$), independently of crop size or canopy density. That system
88 would avoid the problem of over dosage of PPP detected as a frequent problem in the
89 early crop growth stages, especially in orchards and vineyards where in most cases
90 pesticide dose rate is expressed in many different ways (Koch, 2007).

91 But in any case selective application with a precise target detection system must
92 assure uniform deposits and must guarantee that large savings in sprayed application
93 volume rates will not affect biological efficacy. This assumption has been confirmed in
94 trials using different electronic control strategies (Koch and Weisser, 2000) who
95 obtained no significant differences between a sensor based and a conventional
96 application technique for apple scab (*Venturia inaequalis*), pear psylla (*Cacopsylla pyri*
97 *xx*) and leaf and bud mite (*Aculus schechtendali xx*) control.

98 This paper describes the characteristics of a sprayer prototype able to
99 automatically adapt the spray application rate according to the target geometry, using an
100 adapted tree-row-volume (TRV) estimation method (Pergher and Petris, 2008; Rüegg et
101 al., 1999). Results in terms of deposit of tracer ($\mu\text{g}\cdot\text{cm}^{-2}$) and leaf recovery (actual
102 recovered tracer compared with the expected according leaf area) have been calculated
103 and compared with those obtained with a conventional method based on a per land
104 surface dosage system ($\text{l}\cdot\text{ha}^{-1}$). In order to evaluate the influence of the leaf morphology,
105 research trials have been conducted in three representative vineyards (*cv. Merlot*, *cv.*
106 *Cabernet Sauvignon* and *cv. Tempranillo*) at two growth stages.

107 The objectives of this research were: a) to analyze the ability of ultrasonic
108 sensors in determining vineyard structure; b) to investigate the spray volume savings
109 achieved through the use of a target measurement sprayer control system based on the
110 instantaneous vine volume, *iVV* (an adapted VRV principle); to evaluate the efficiency
111 of the proposed spraying system, in comparison with the conventional application based
112 on land surface; and d) to determine the relationship between spray volume savings and
113 canopy structure.

114

115 **2. Material and methods**

116 *2.1. Sprayer design*

117 The development and testing of the target measurement and sprayer control
118 system used in this research have been previously described and discussed (Gil et al.,
119 2007) and will only be briefly outlined in this article. The measurement system and the
120 electronic process unit were mounted on an air-blast orchard sprayer (Hardi LE-600
121 BK/2 with a centrifugal fan of 400 mm diameter). The sprayer was equipped with six
122 individual and adjustable spouts (three on each side of the machine) in which up to five

123 nozzles could be arranged on each one. A mast was fitted on its left side to hold three
124 ultrasonic sensors and a solenoid high frequency electro valve was in front of each of
125 the three spouts linked to each ultrasonic sensor. The three sensors and electro valves
126 were connected to the central control unit placed on the rear top of the sprayer on which
127 a purpose developed software based on LabVIEW (National Instruments Corporation,
128 Austin, USA) was used to transform the crop width measured by each sensor into flow
129 rate at every nozzle set (Figure 1) according equation [1]:

$$130 \quad q_u = \frac{C_w \times \frac{C_h}{3} \times v \times m \times 1000}{60 \times n} \quad [1]$$

131

132 Where C_w is the half crop width (m), C_h crop height (m), v is forward speed ($\text{km}\cdot\text{h}^{-1}$), m
133 the application coefficient per unit vegetation volume ($\text{l}\cdot\text{m}^{-3}$) and n the number of
134 nozzles per manifold (equal to 2).

135

136 2.2. Experimental plots

137 Trials were conducted in three different grape varieties (*Merlot*, *Cabernet*
138 *Sauvignon* and *Tempranillo*) and at two different growth stages (75 and 85 according to
139 the BBCH-scale (Meier, 2001). In all cases a total length of at least 100 m of five rows
140 were sprayed (1,500 m^2 of experimental plot), and sample leaves for deposit
141 measurements were only taken from the three different blocks randomly established in
142 the center row. In every block, a sample of 1 m length of row was established, on which
143 plants were divided into four different zones according to height (every 0.40 m, ranging
144 from 0.40 m to 1.60 m), and three zones according to depth within the crop (I: external
145 left, II: centre; and III: external right). From each of the twelve sampling positions
146 (Figure 2), three replicates of samples were collected after spraying and stored in plastic
147 bags.

148

149 2.3. *Treatments*

150 A set of tests was arranged on each variety and growth stage in order to compare
151 the efficiency of application of the variable rate system with a conventional spraying
152 procedure based on a constant application volume rate ($l \cdot ha^{-1}$) selected for each situation
153 according to the usual rates in the area and growth stage. For the variable rate system,
154 the application coefficient of $m = 0.095 l \cdot m^{-3}_{vegetation}$ was maintained in all cases. This
155 application rate was selected according to previous research (Gil, 2001) where interest
156 and benefits of this value in terms of efficacy and efficiency of applications were
157 demonstrated. The sprayer settings (Table 1) were maintained as close as possible
158 between treatments in order to avoid external sources of variability.

159

160 2.4. *Leaf area measurements*

161 The leaf area index (*LAI*) was measured for each variety after the trials. For this
162 purpose, two replicates of 1.0 m length were randomly selected among the five treated
163 rows and leaves were picked independently into four plastic bags, corresponding to the
164 four crop sample zones from 0.4 m to 1.6 m height (Figure 2). The total weight of each
165 individual leaf sample was determined in the laboratory. The leaf area index was
166 determined by area: weight ratio estimation for each variety and crop stage (Gil et al.,
167 2007; Cross et al., 2001). All the obtained relationships were determined by measuring
168 the weight and surface area of 50 samples collected from the bottom, middle and top
169 parts of the vine. Surface area (one side only) was measured with a LI-COR LI 3100C
170 electronic planimeter.

171

172 2.5. *Measurement of deposits*

173 Deposit and spatial distribution of spray liquid was measured using EDTA
174 metallic chelates (Mn for conventional application and Zn for the variable rate system)
175 as spray tracers (Gil et al., 2005; Gil et al., 2007; Cross et al., 2001; Murray et al., 2000)
176 at a rate ranging from 0.68 to 1.80 g·l⁻¹ depending on treatment (Table 1) following the
177 same protocol established by Gil et al. (2007). Spraying different tracers for each
178 treatment allowed the same leaf samples to be used and reduces the effect of canopy
179 variability (Murray et al., 2000; Solanelles et al., 2005). Prior to the application, 25
180 leaves were picked from every individual block as blank samples, in order to determine
181 the possible presence of metals. In all cases values of tracer concentration in the blank
182 samples were less than the detection limit of the spectrophotometer (< 0.01 ppm). Once
183 collected, all plastic bags containing leaf samples were placed in a dark container and
184 stored in a refrigerator until the extraction process. Collection of samples was
185 completed within 2 hours after the last application. Tracer deposit d in $\mu\text{g}\cdot\text{cm}^{-2}$ was
186 determined by adding an exact quantity of deionized water as extractant (100 ml) and
187 the subsequent measurement of tracer concentration using an atomic absorption
188 spectrometer (Variant Spectra 1100). Three samples of roughly 100 ml of the spray
189 solution for each treatment were taken from the tank of the sprayer immediately before
190 and after application in order to determine the real tank concentration for each metal.

191

192 *2.6. Analysis and expression of results*

193 Statistical analysis was performed using SAS system v.8 (SAS Institute Inc.,
194 Cary, NC, USA). The symbols used are reported in the notation table using a previously
195 defined nomenclature (Pergher and Gubiani, 1995).

196 The amount of spray deposited per unit leaf area by a particular treatment (d ,)
197 was calculated by dividing the tracer concentration in the washing solution of sample
198 (T_{cl}) by the total leaf area of the sample L_a , according equation [2]

$$199 \quad d = \frac{T_{cl} \times w}{L_a} \quad [2]$$

200

201 where d is the tracer deposit per unit leaf area ($\mu\text{g}\cdot\text{cm}^{-2}$), T_{cl} tracer concentration in
202 washing solution of sample leaf ($\mu\text{g}\cdot\text{l}^{-1}$), w the amount of deionized water (ml) and L_a
203 area of sample leaf (cm^2)

204 Since the tracer application rates (T_{cs}) were not the same for all treatments, a
205 normalized deposit, d_n ($\mu\text{g}\cdot\text{cm}^{-2}_{leaf} / \mu\text{g}\cdot\text{cm}^{-2}_{ground}$) was then calculated according to
206 equation [3], by dividing the actual deposit d by the amount of metal tracer applied per
207 unit ground area:

$$208 \quad d_n = \frac{d \times 10^5}{V \times T_{cs}} \quad [3]$$

209

210 where d_n is the normalized tracer deposit rate per unit leaf surface ($\mu\text{g}\cdot\text{cm}^{-2}$), d the actual
211 deposit per unit area of leaf surface ($\mu\text{g}\cdot\text{cm}^{-2}$), V the spray volume rate ($\text{l}\cdot\text{ha}^{-1}$) and T_{cs}
212 the tracer concentration of spray mixture in the tank ($\mu\text{g}\cdot\text{l}^{-1}$)

213 The normalized deposit procedure enables comparisons between the different
214 sprayers and/or the different technologies, and has been based on the total amount of
215 tracer applied per ground area. This procedure has been previously applied (Cross et al.,
216 2001; Viret et al., 2003; Siegfried et al., 2007) where comparisons between sprayers
217 and/or field conditions were arranged.

218 At the same the proportion of spray retained on the leaves (D_l) was also
219 calculated (equation [4]) according the equation used by Pergher and Gubiani (1995),
220 Cross et al. (2001) and Gil et al. (2007):

$$221 \quad D_l = \frac{d \times 10^7 \times LAI}{V \times T_{cs}} \quad [4]$$

222

223 In all cases, values of tracer concentration measured on blank samples were included in
224 the calculation and normalization procedure. Prior to statistical analyses, a normal
225 adjustment of the obtained data using a logarithmic transformation was applied in order
226 to stabilize variances (Doruchowski et al., 1996; Gil et al., 2007).

227

228 **3. Results**

229 *3.1. Quantification of savings*

230 One of the objectives of this research was to calculate the total savings in the
231 applied liquid. According to the application rate adjusted for every individual test, Table
232 2 shows the individual and average saving of liquid for all varieties and crop stages. In
233 all cases saving values are greater than 40%, with the highest value for cv. *Tempranillo*
234 (77%) in the last growth stage (BBCH-scale 85). In this particular situation some
235 pruning before the test probably affected the measurements obtained by the sensors,
236 increasing the distance to the crop and reducing substantially the applied volume (86
237 l·ha⁻¹) compared to previous applications, whereas the conventional application volume
238 rate was increased according to the normal procedure in the area. In general, the average
239 savings obtained were approximately 58%, being in accordance with previous research
240 (Koch and Weisser, 2000; Gil et al., 2007; Moltó et al., 2000; Balsari and Tamagnone,
241 1998; Solanelles et al., 2005). A detailed reading of results shown in Table 3 indicates a
242 good correlation between canopy volume and leaf recovery in variable rate application,

243 giving better results for highest values of TRV (Figure 3) measured according the
244 methodology proposed by Siegfried et al. (2007).

245 The spatial distribution of savings can be observed in Figure 4. As an example,
246 this figure shows a sample of 20 meters of crop line (*cv. Merlot*) where all the measured
247 points with ultrasonic sensors have been represented (every 80 ms corresponding to 10
248 cm along the crop line). For every measured point the applied volume in variable rate
249 application mode, calculated according to the measured distance with sensors, can be
250 compared with that applied with the conventional spraying mode. Differences between
251 those two lines represent the savings of liquid. It is important to highlight the perfect
252 similitude of liquid amount delivered by the variable application method with the crop
253 profile line. In figure great differences can be observed between the two applied volume
254 rates. However, in any case those savings must be analyzed and evaluated together with
255 averaged deposit values obtained for the two tested methodologies.

256

257 3.2. *Deposit on leaves*

258 According to the obtained values of normalized deposit on leaves d_n ,
259 proportional leaf recovery D_l and spatial uniformity of deposit on the whole canopy
260 measured by the coefficient of variation of total deposit samples (Table 3), the variable
261 rate application method showed higher leaf deposits in all cases except for those
262 obtained for *cv. Merlot*. For the remaining cases, differences in d_n between the two
263 tested methods differ significantly in favor of the variable rate method. In terms of
264 proportion of spray retained (D_l), the same tendency has been observed. In all cases,
265 variable application method gave the highest values of retention, always greater than
266 40%. It is interesting to remark the highest value of proportional leaf recovery (86.85%)

267 obtained in cv. *Tempranillo* at 75 of BBCH-scale. On the contrary, retention values
268 obtained with conventional applications were below 40%, except for cv. *Merlot*.

269 The spatial uniformity of leaf deposit in the whole canopy, measured by means
270 of the coefficient of variation (CV %) of the total deposit samples on the crop (Table 3)
271 indicates that in cv. *Tempranillo* and *Cabernet Sauvignon*, variable rate applications
272 gave CV values under 50%, with a more uniform deposit than obtained for conventional
273 applications. For cv. *Merlot*, the tendency was the opposite: conventional applications
274 gave the most uniform results.

275 Graphics of the spatial distribution of leaf deposit within the canopy are shown
276 in Figure 5. In general, high uniformity can be observed in all cases, independently of
277 the spray method (conventional or variable), crop stage or crop variety. A deeper
278 analysis of figure 5 indicates higher values of normalized leaf deposits for the variable
279 rate application method than those obtained with the conventional method.

280 The effect of variable rate applications on the quality of leaf deposits measured
281 by the coefficient of variation of the total sample zones on the vine (d_n) and the
282 normalized leaf recovery expressed as a percentage of the total emitted output (D_l), are
283 shown in Figure 6. The general tendency indicates a slow but homogeneous movement
284 to the right of the graph, which means an increase in normalized leaf recovery, obtained
285 in all cases with the lower volume rates. The diameter of each individual circle
286 represents the average normalized deposit (d_n) on each treatment. Following the same
287 trend as observed for leaf recovery, the variable rate technology gives the highest values
288 of normalized deposit. And in terms of uniformity of deposits, in general all the circles
289 are located close to the center line (horizontal), meaning similar values of uniformity
290 (coefficient of variation).

291 A detailed analysis of the distribution of sample frequencies was conducted in
292 order to compare the normalized deposit in both methods. It is interesting to notice that
293 in all cases variable rate applications gave higher cumulative frequencies of leaf
294 samples with higher deposits. Remarkable results have been obtained at the earlier crop
295 stage (BBCH-75) in *cv. Cabernet Sauvignon* and *cv. Tempranillo*.

296

297 3.3. Crop profile and liquid distribution

298 Figure 7 shows the relation between crop profile (leaf surface distribution with
299 height) and total deposits measured at each crop level. In general in all cases it can be
300 observed how deposits for conventional application follow a vertical line, independently
301 of leaf distribution on each level. Those lines must be compared with those related to
302 variable rate application, which present in general better adaptation to leaf distribution.
303 Quantification of this adaptation can be done by means of the coefficient of correlation
304 (r) between profiles (Figure 7). In all cases, except in the latest crop stage in *cv.*
305 *Tempranillo*, variable rate spraying offered better adaptation to crop profile or at least
306 the same values as conventional spraying (i.e. *var. Merlot*).

307 Another important aspect regarding the relationship between crop structure and
308 applied volume can be observed in Figure 8, representing values obtained in *cv. Merlot*.
309 In that figure, variation of the real application coefficient m ($l \cdot m^{-3}$) has been plotted
310 together with the obtained measures of canopy volume (m^3) with the ultra sonic sensors.
311 Solid line on the graphic indicates the theoretical m value for which the variable rate
312 sprayer was adjusted. Values of real m ($l \cdot m^{-3}$) rate delivered with the variable rate
313 system have been represented with triangles on the same graphic. Results show a great
314 coincidence with the objective, mainly in situations with a high canopy volume (right
315 part of the figure). The most important deviations from the intended objective can be

316 observed for situations with low or very low crop canopy (left part of the figure). This
317 behavior is due to spraying those areas with the minimum established pressure
318 (sometimes overdosing) to ensure the quality of the droplets. Obtained results in
319 conventional application (represented by square points on the graph) indicates that the
320 objective is only achieved for canopy values over 0.04 m^3 with high overdose generated
321 in case of lower canopy volumes. In fact, this behavior is the expected in a constant
322 flow rate application. The selected flow rate is the one that best fits worst cases (highest
323 canopy volumes) found in the vineyard. As the sprayed flow rate does not vary with
324 canopy volume decrease, the result is an over sprayed canopy in situations different than
325 the worst case. The application coefficient increases as the canopy decreases.

326

327 **4. Discussion**

328 Even in uniform vineyards, important differences can be observed in crop width
329 and thus in canopy volume along the line. The use of electronic systems capable to
330 determine these differences in real time and the ability to adjust the working parameters
331 according to these variations is an interesting way to achieve savings in the total amount
332 of sprayed pesticides.

333 The use of ultrasonic sensors together with variable rate electro-valves and the
334 corresponding software for automation, made possible a real time modification of the
335 spray flow rate according to the canopy volume. This allowed a significant reduction in
336 spray volume while maintaining coverage and penetration rates similar or even better to
337 conventional methods.

338 Ultrasonic sensors and their measurements of crop canopy allow tracer deposits
339 to be varied according to leaf distribution in the crop profile. This fact is extremely
340 important in order to obtain leaf deposits close to the intended threshold.

341 Results obtained in all crop conditions and varieties encourage the continuation
342 of this research, maintaining as the main goal of increasing pesticide savings and
343 improved liquid distribution according to the crop characteristics.

344

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351

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452

453

454 TABLES

455 Table 1 Operational parameters during treatment applications

Variety and crop Stage *	Conventional application			Variable rate application (VRT)		
	Applied volume rate (l·ha ⁻¹)	Pressure (bar)	Tracer concentration (mg·l ⁻¹ Mn)	Application rate <i>m</i> (l·m ⁻³)	Pressure (bar)	Tracer concentration (mg·l ⁻¹ Zn)
Merlot 85	266	7.0	1878			1568
Cabernet 75	299	7.0	741			1021
Sauvignon 85	373	11.0	735	0.095	min = 3.0	680
	75	299	7.0		max = 7.0	1021
Tempranillo 85	373	11.0	735			680

456 In all cases the sprayer was settled with 12 hollow cone nozzles (Albuz ATR brown) at

457 a forward speed of 4.5 km·h⁻¹

458 * Crop stage according to BBCH classification

459

460 Table 2 Percentage savings (VRT/conventional) for different cultivars and crop stages

Variety and crop stage*	Application rate (l·ha ⁻¹)		Total saving (%)
	Conventional	VRT	
Merlot 85	266	141	47.0
Cabernet 75	299	179	40.1
Sauvignon 85	373	111	70.2
	75	127	57.5
Tempranillo 85	373	86	76.9

461 * According to BBCH classification

462 Table 3 Normalized deposit average values, proportional leaf recovery and coefficient of variation for all varieties and crop stages analyzed

Variety and crop stage ¹	LAI	TRV ² (m ³ ·ha ⁻¹)	Actual deposit ³		Normalized deposit ⁴		Proportion of spray retained D_t (%)		Deposit uniformity (CV %)		
			d		d_n		CONV	VRT	CONV	VRT	
			CONV	VRT	CONV	VRT	CONV	VRT	CONV	VRT	
Merlot	85	1.32	1880	2.30	0.77	0.46 a	0.35 b	60.85 a	47.14 b	28.00	54.00
Cabernet	75	1.08	1922	0.73	1.02	0.33 b	0.56 a	35.51 b	60.94 a	50.44	38.73
Sauvignon	85	0.99	1514	1.01	0.39	0.37 b	0.52 a	37.51 b	51.46 a	32.27	34.94
Tempranillo	75	1.24	2242	0.66	0.89	0.30 b	0.69 a	37.45 b	86.85 a	51.12	43.15
	85	1.50	1710	0.77	0.16	0.28 a	0.28 a	43.38 a	42.23 a	45.46	49.76

463

464 CONV: Conventional application; VRT: Variable Rate Technology

465 Values followed by the same letter in rows do not differ statistically (Student-Neuman-Keuls test, $p < 0.05$)

466 ¹According to BBCH classification

467 ²Calculated according methodology proposed by (Siegfried et al., 2007)

468 ³ Actual deposit (d) expressed as total amount of tracer per leaf surface e unit ($\mu\text{g}\cdot\text{cm}^{-2}$)

469 ⁴ Normalized deposit (d_n) is expressed by relation between the total tracer on the leaf surface and the total amount of tracer per ground unit
 470 ($\mu\text{g}\cdot\text{cm}^{-2}_{\text{leaf}} / \mu\text{g}\cdot\text{cm}^{-2}_{\text{ground}}$)

FIGURE CAPTIONS

Figure 1 Principle of functioning of the prototype (left) and prototype with electronic devices (right).

Figure 2 Sampling zone on the canopy (left) and defoliation procedure for the leaf area index determination (right).

Figure 3 Relationship between the measured tree row volume (Siegfried *et al*, 2007) and the proportion of spray retained (%) for conventional application (left) and variable rate application (right).

Figure 4 Variation of nozzle flow rate in variable rate application, according crop structure measured by the ultrasonic sensors. Horizontal line represents the constant nozzle flow rate emitted during conventional application.

Figure 5 Spatial distribution of normalized deposit (d_n) for conventional and variable rate application for different vines and crop stages within the canopy.

Figure 6 Relation between variable rate application, leaf recovery and uniformity of deposition. Circumference diameters are proportional to absolute values of leaf deposit.

Figure 7 Vertical profiles of normalized deposits (d_n) and its relation with leaf distribution (% of leaf area). r indicates the coefficient of correlation between profiles.

Figure 8 Actual application coefficients i obtained with the two evaluated methods and comparison with the intended value.

Figure(s)

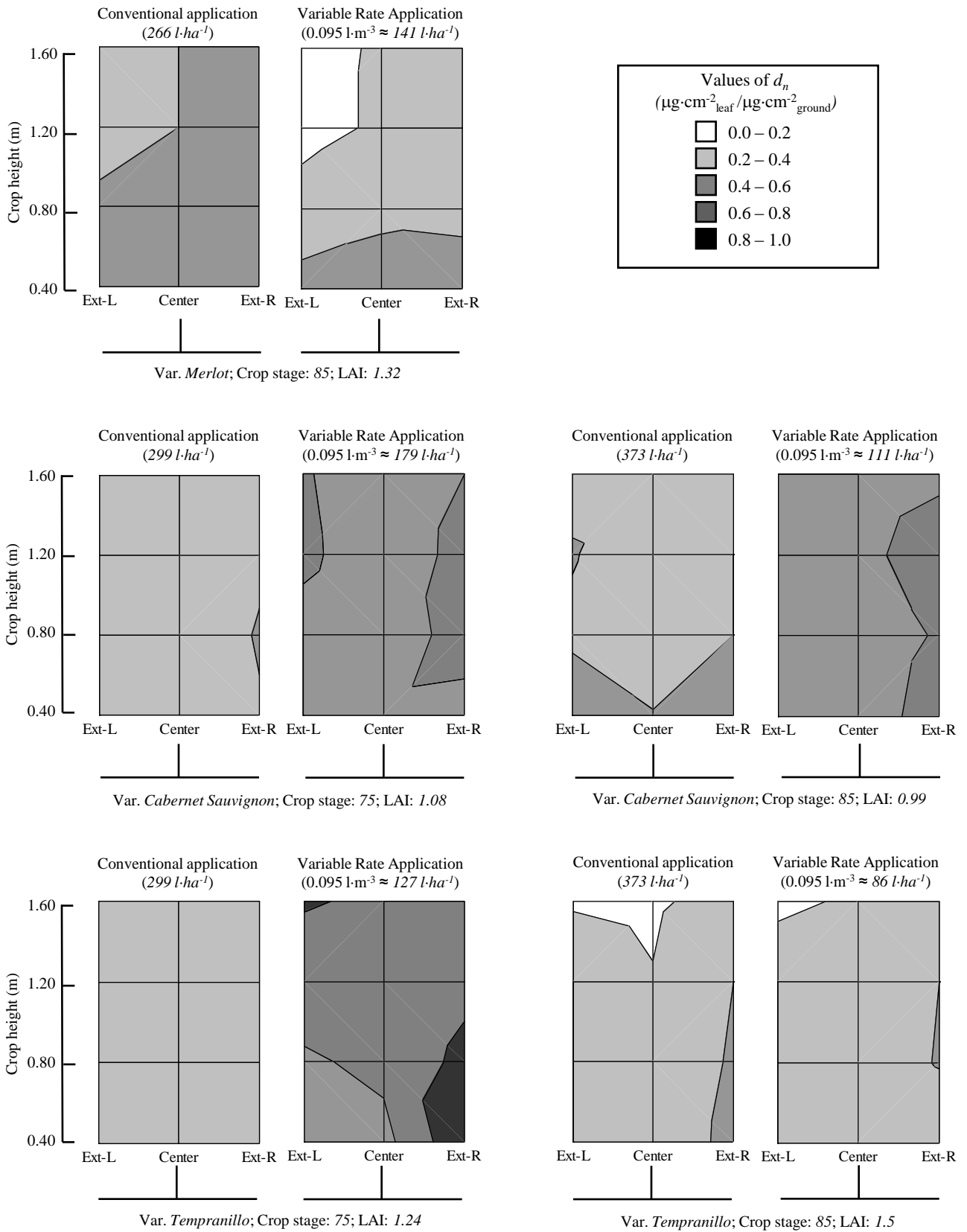
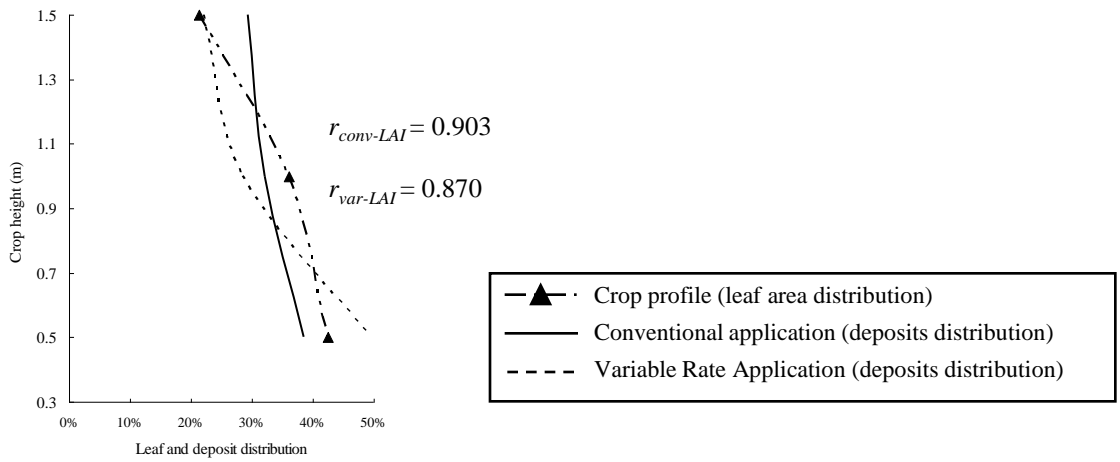
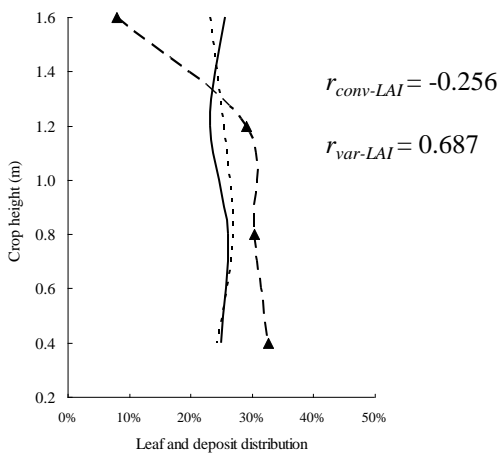


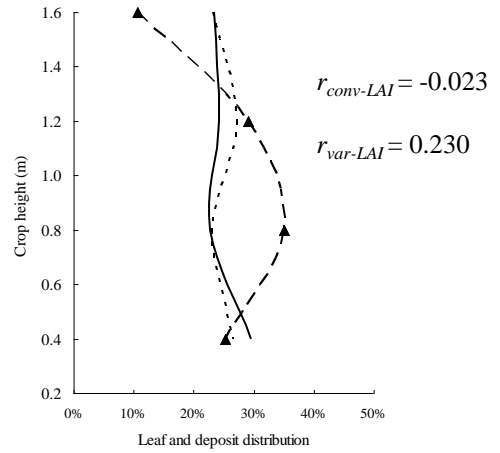
Figure 5



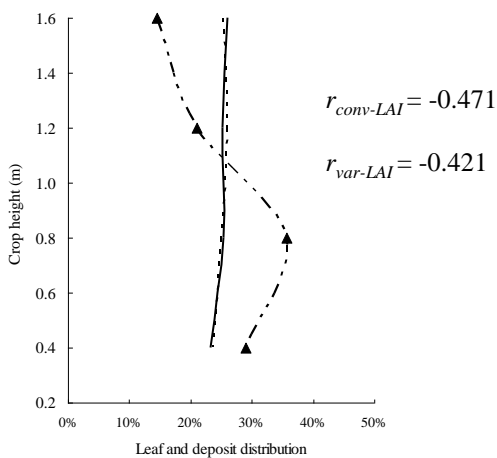
Var. Merlot; Crop stage: 85; LAI: 1.32



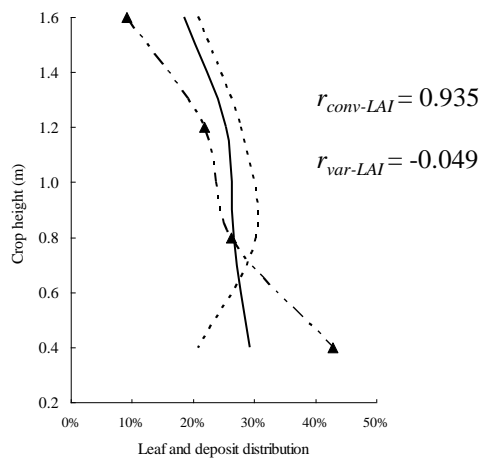
Var. Cabernet Sauvignon; Crop stage: 75; LAI: 1.08



Var. Cabernet Sauvignon; Crop stage: 85; LAI: 0.99



Var. Tempranillo; Crop stage: 75; LAI: 1.24



Var. Tempranillo; Crop stage: 85; LAI: 1.5

Figure 7

Figure(s)

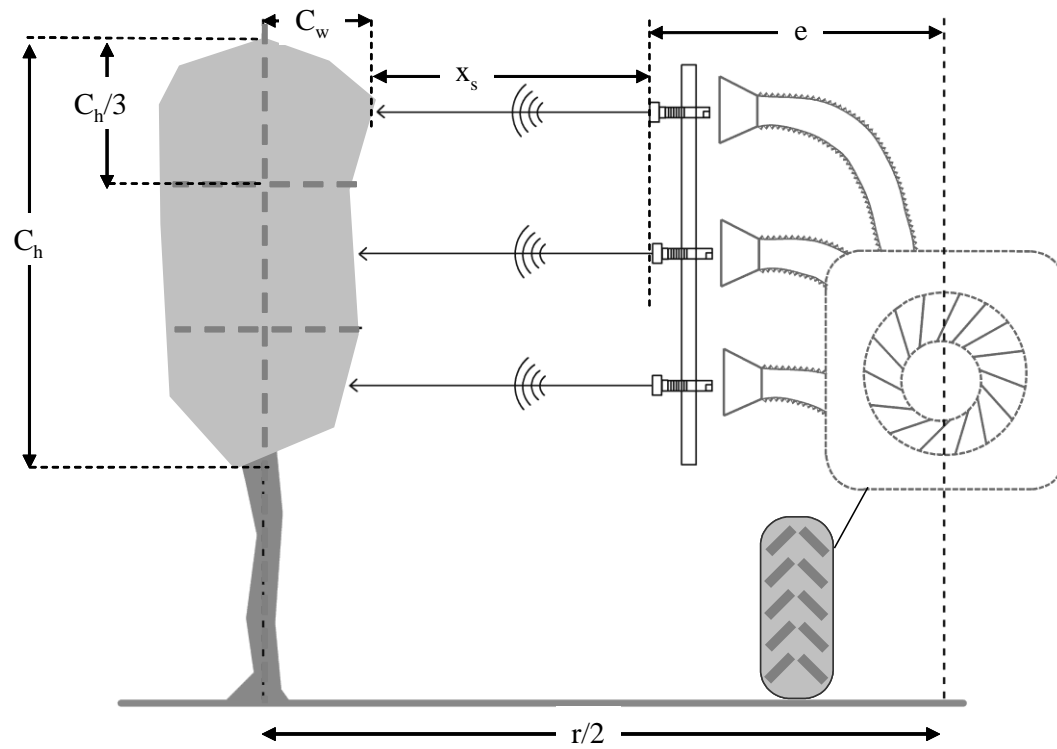


Figure 1

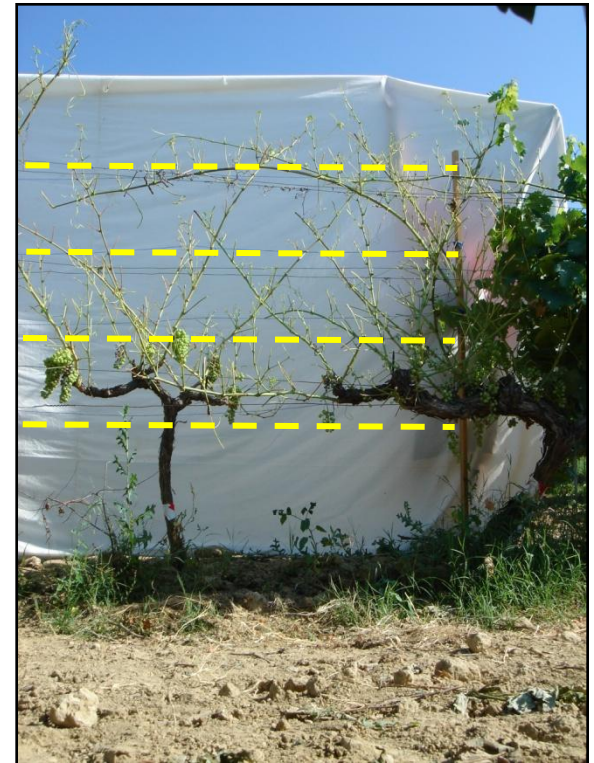


Figure 2

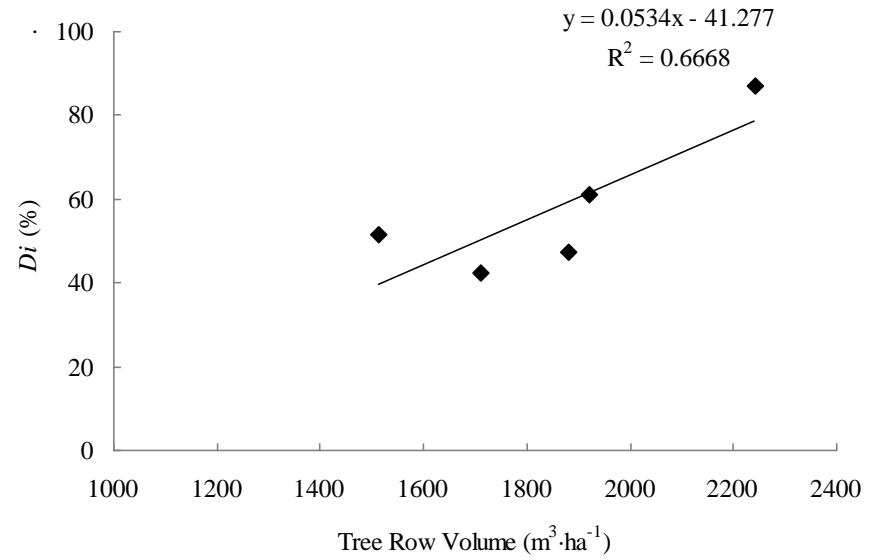
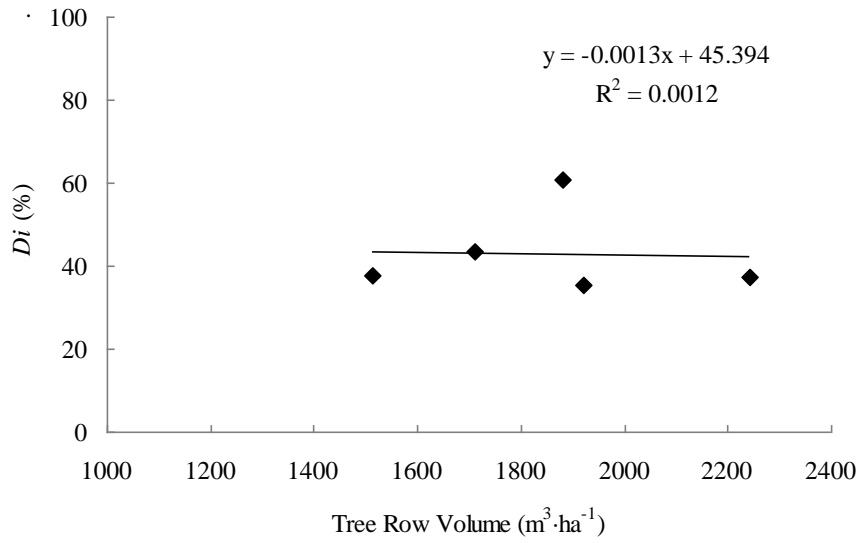


Figure 3

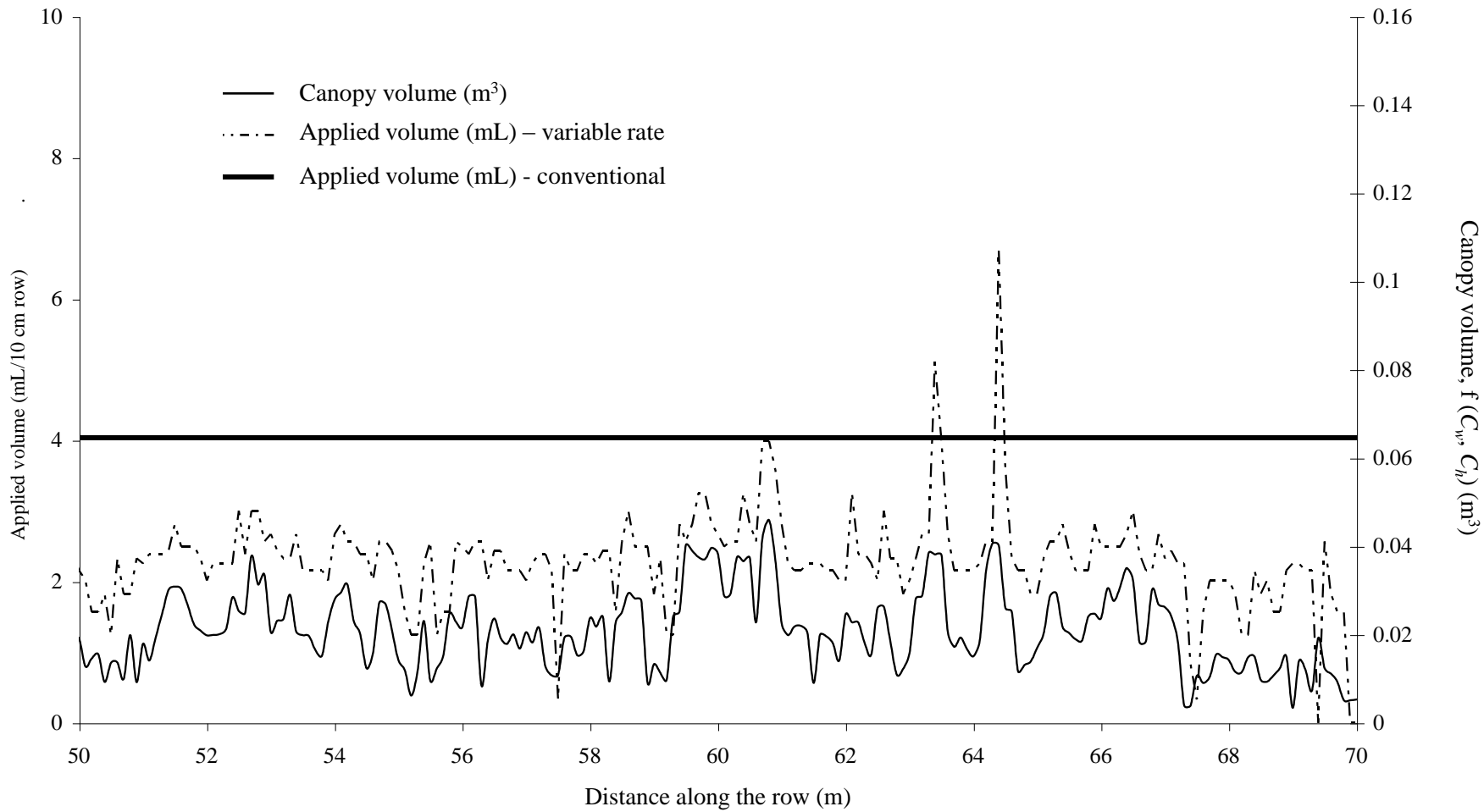


Figure 4

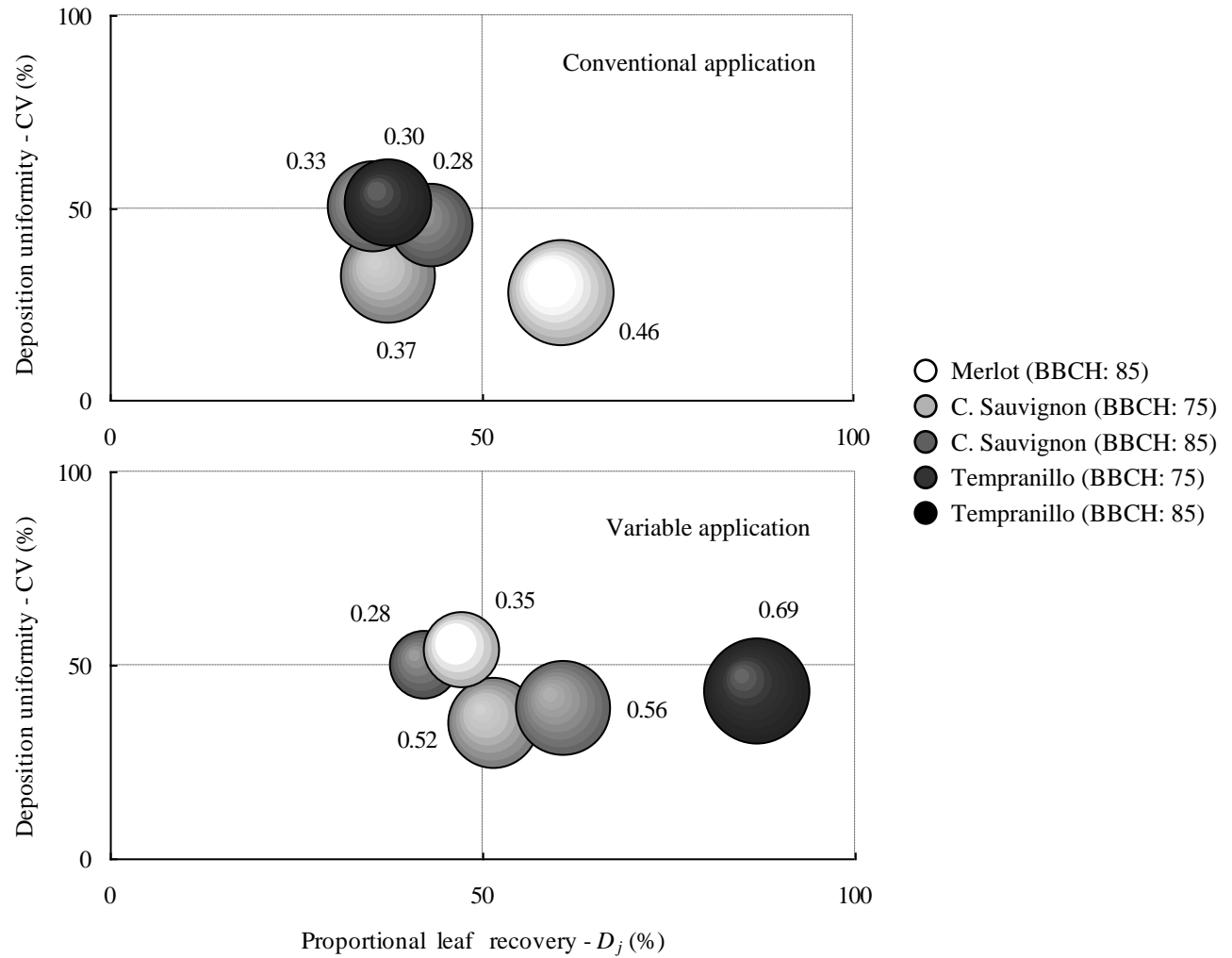


Figure 6

